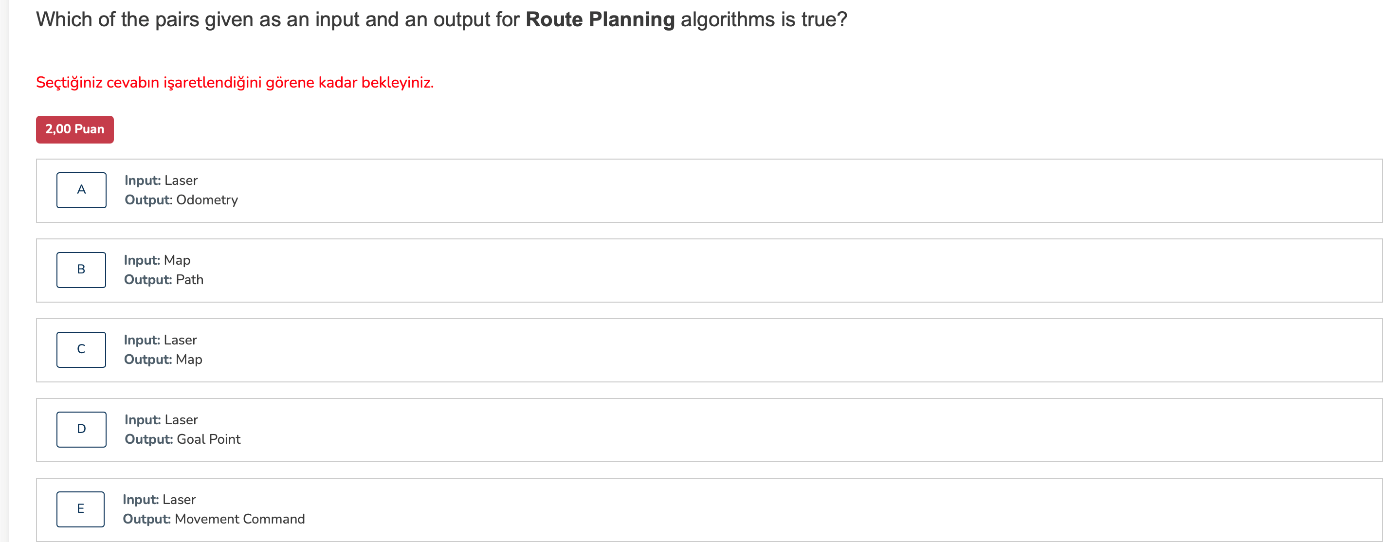
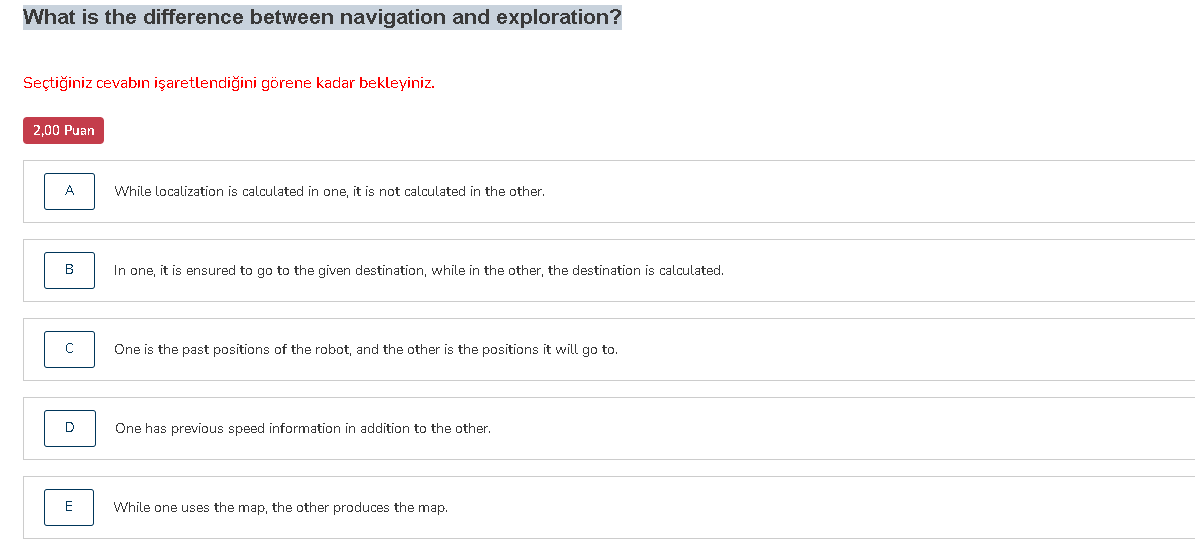
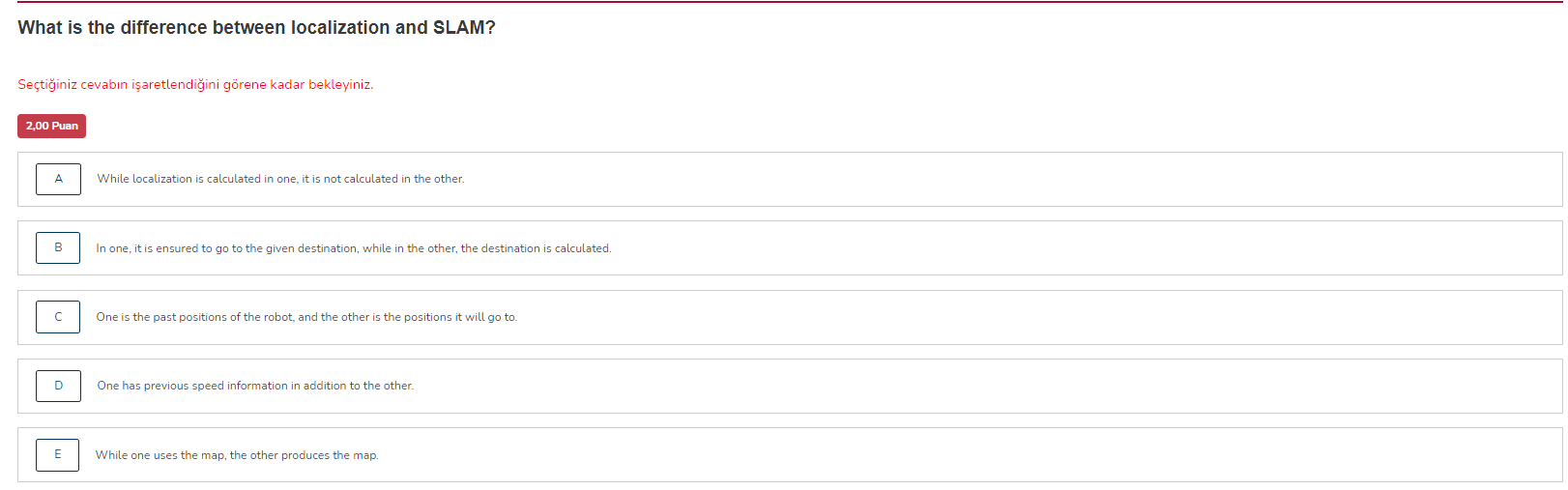
Which of the pairs given as an input and an output for Route Planning algorithms is true??

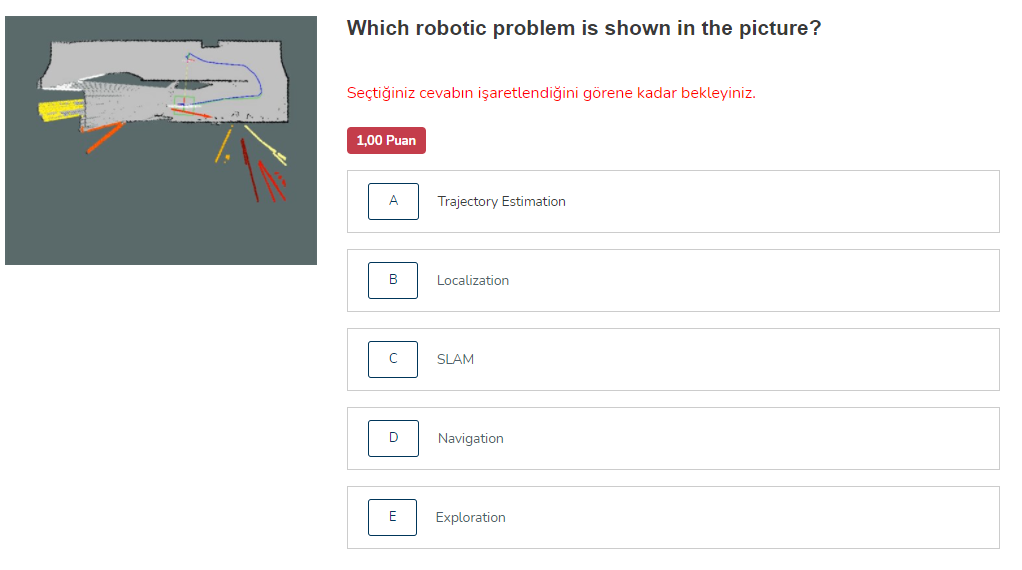
What is the difference between navigation and exploration?



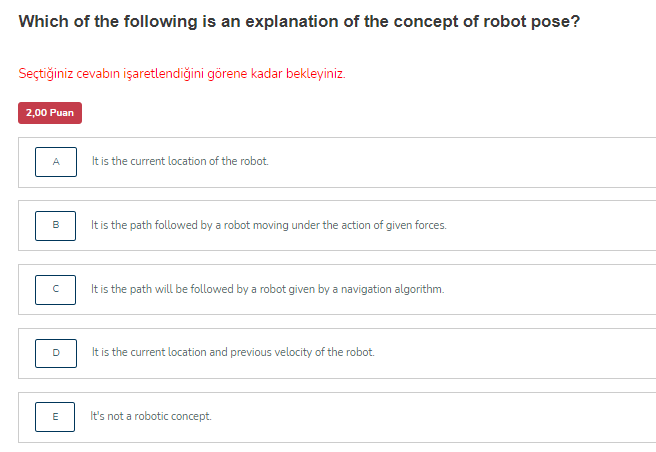
What is the difference between localization and SLAM?



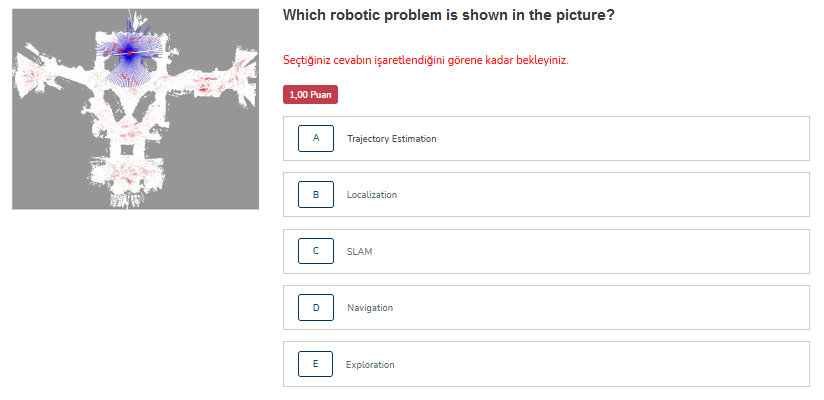
Which robotic problem is shown in the picture??

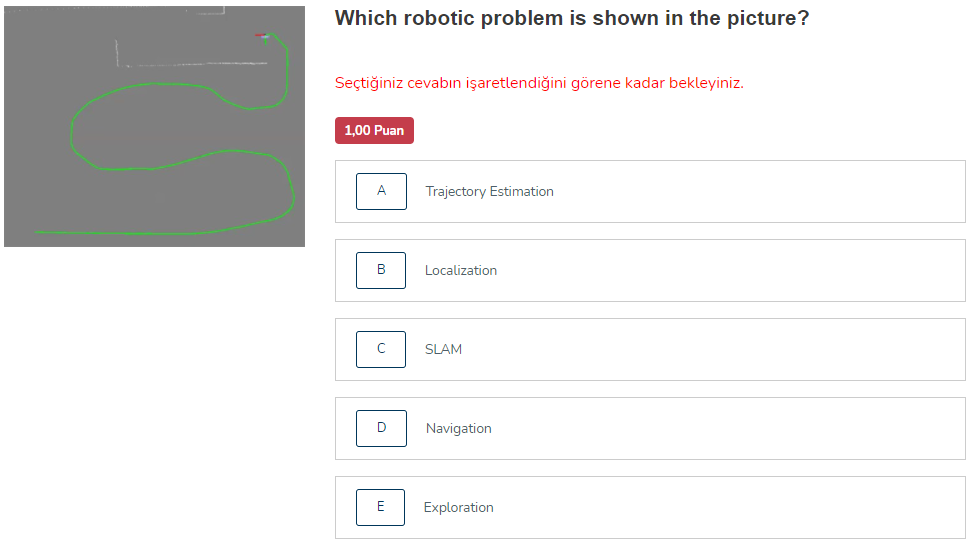
Which of the following is an explanation of the concept of robot pose?

**SPOİLER**

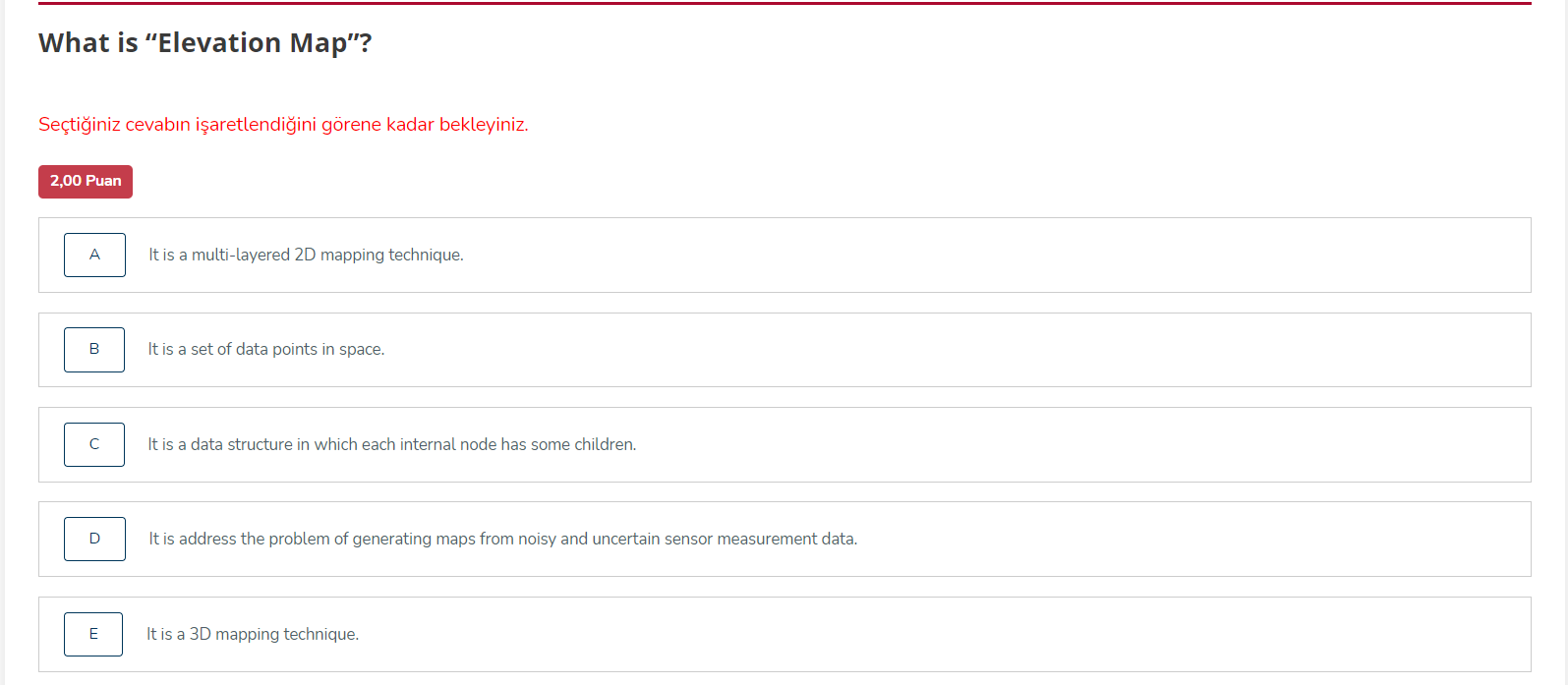


Which robotic problem is shown in the picture??

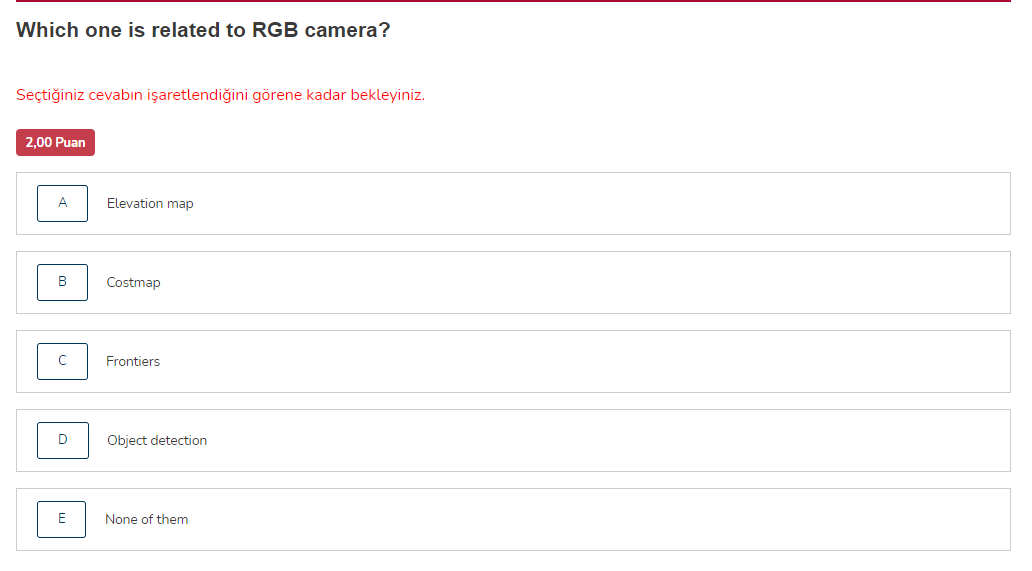




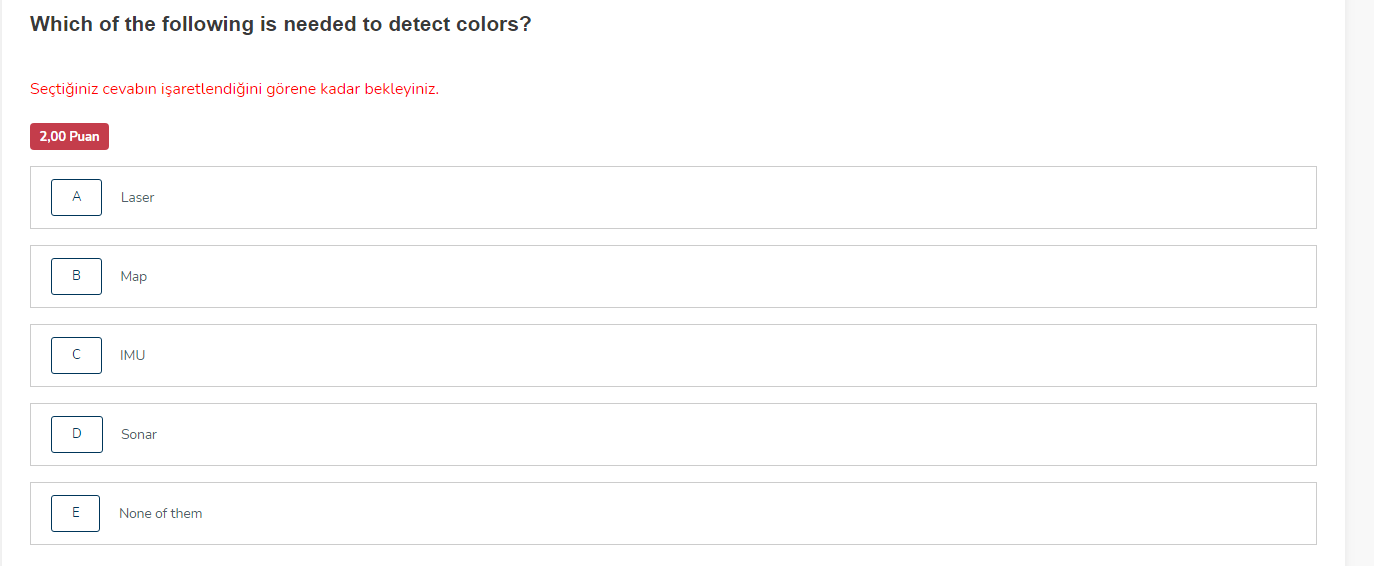
What is “Elevation Map”?



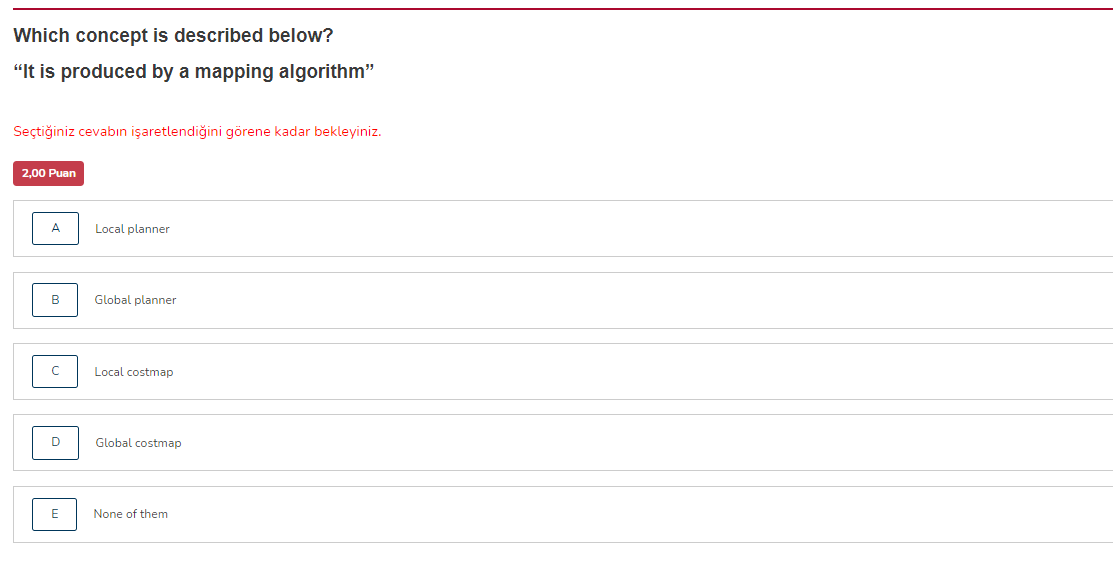
Which one is related to RGB camera??



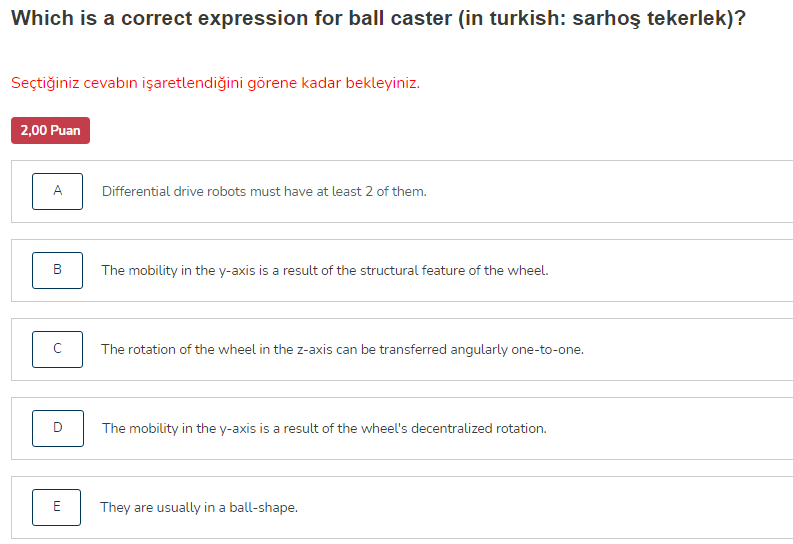
Which of the following is needed to detect colors ??



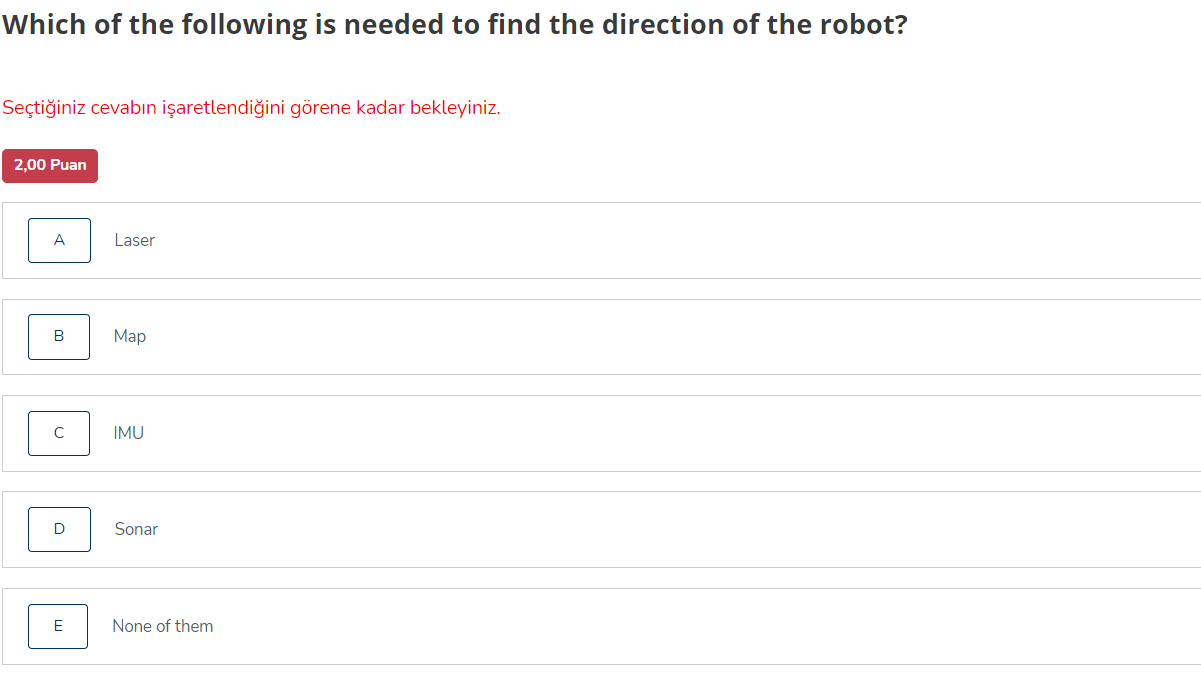
Which concept is described below? “It is produced by a mapping algorithm”



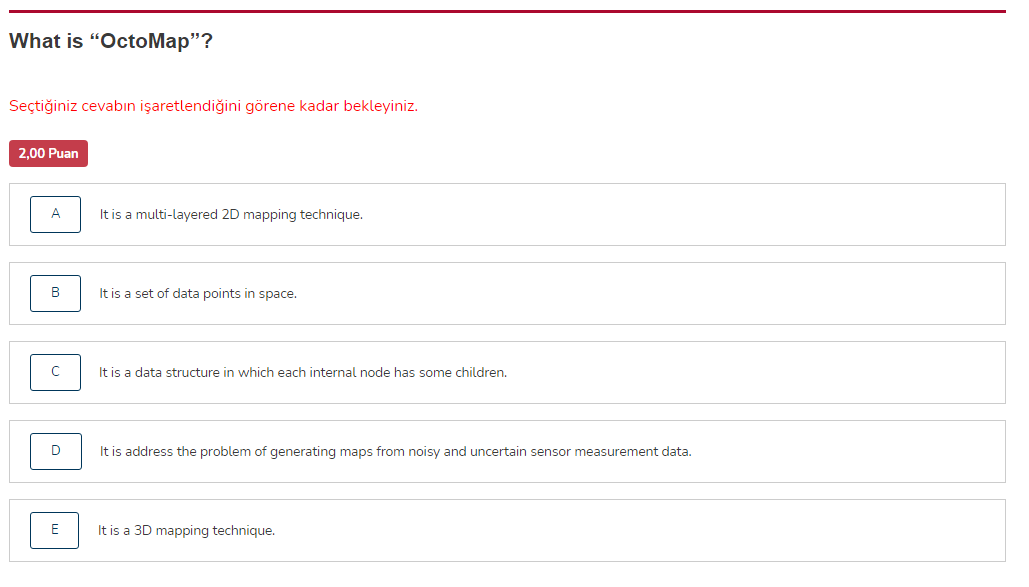
Which is a correct expression for ball caster (in turkish: sarhoş tekerlek)??



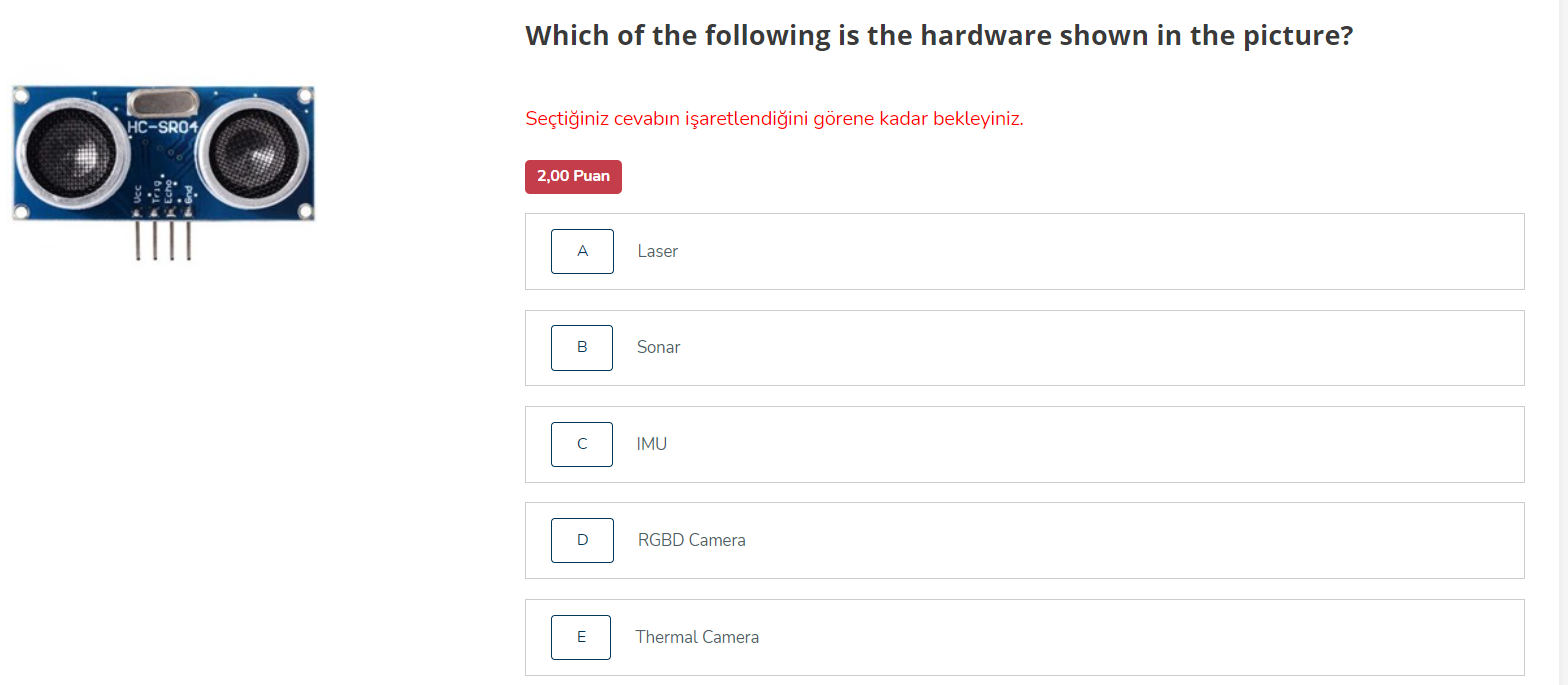
Which of the following is needed to find the direction of the robot?



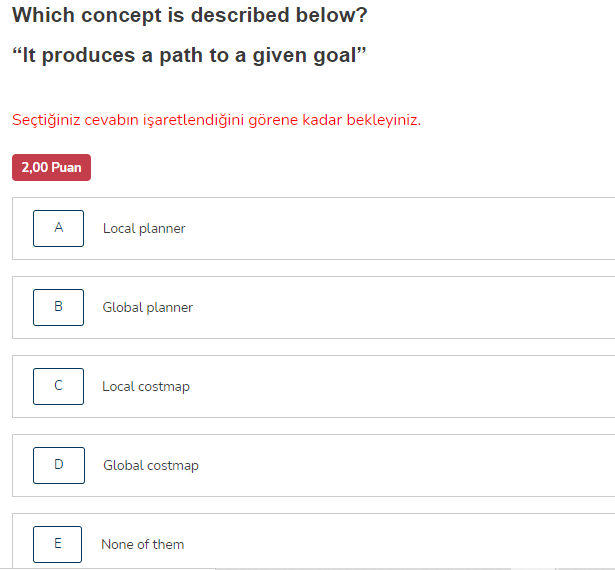
What is “OctoMap



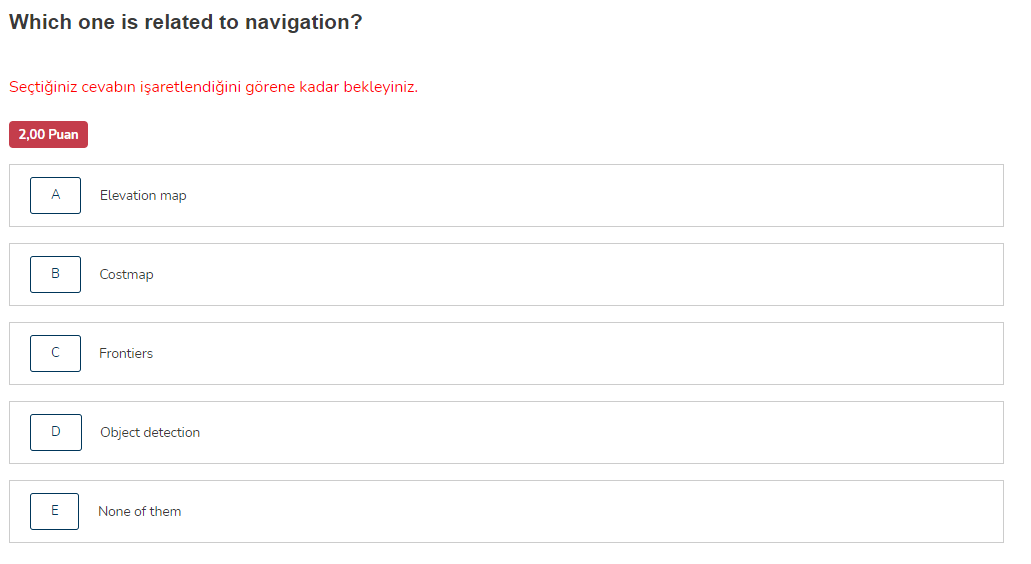
Which of the following is the hardware shown in the picture?



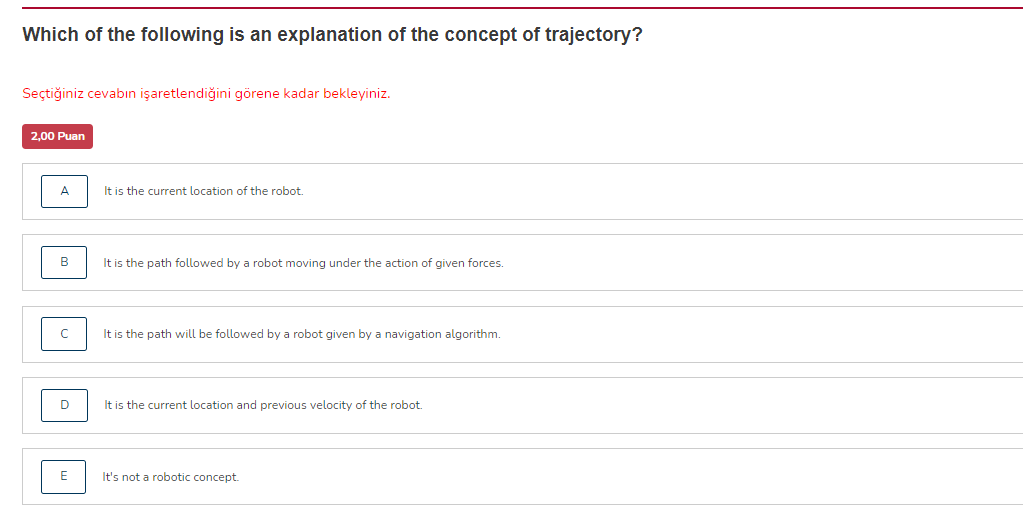
Which concept is described below? “It produces a path to a given goal”



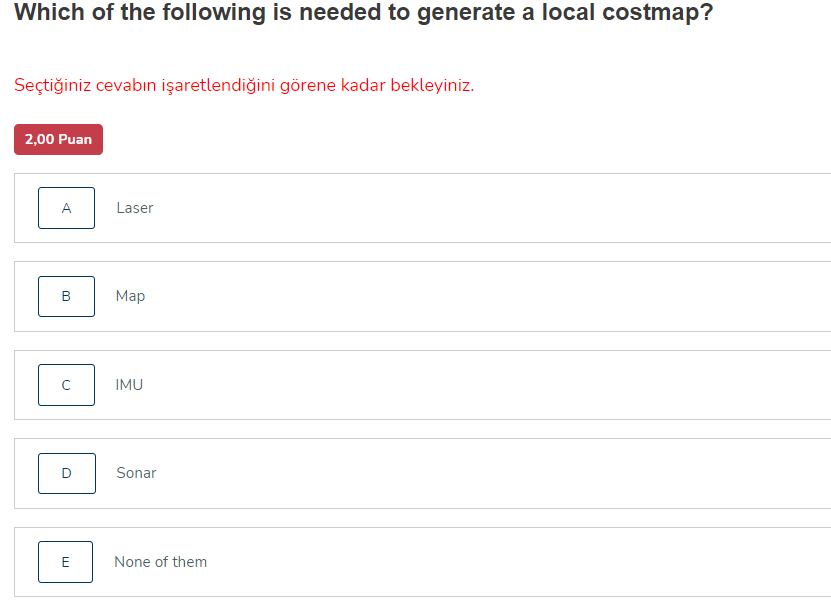
Which one is related to navigation??



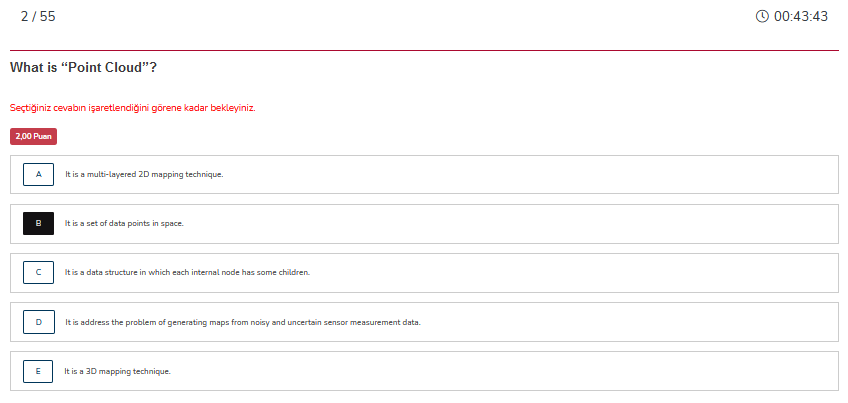
Which of the following is an explanation of the concept of trajectory?



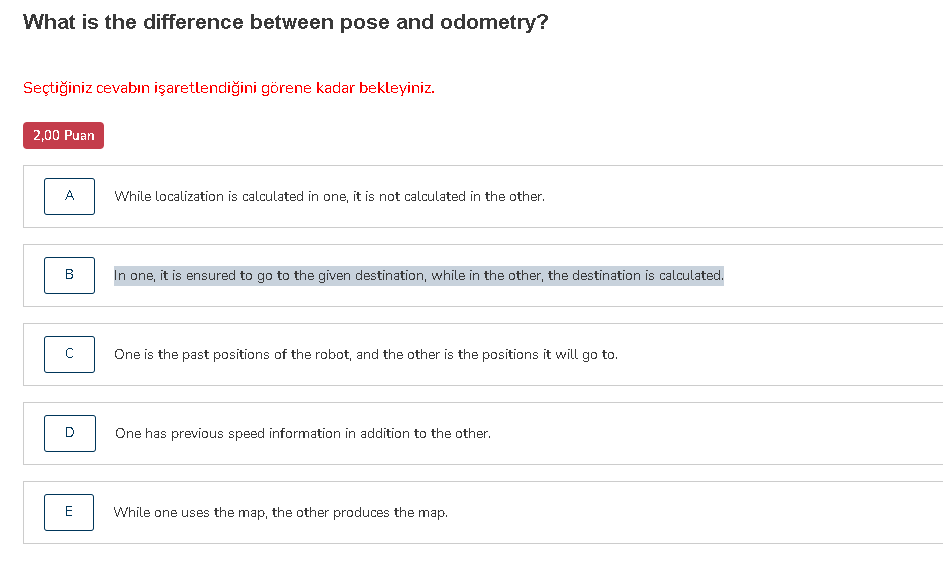
Which of the following is needed to generate a local costmap??



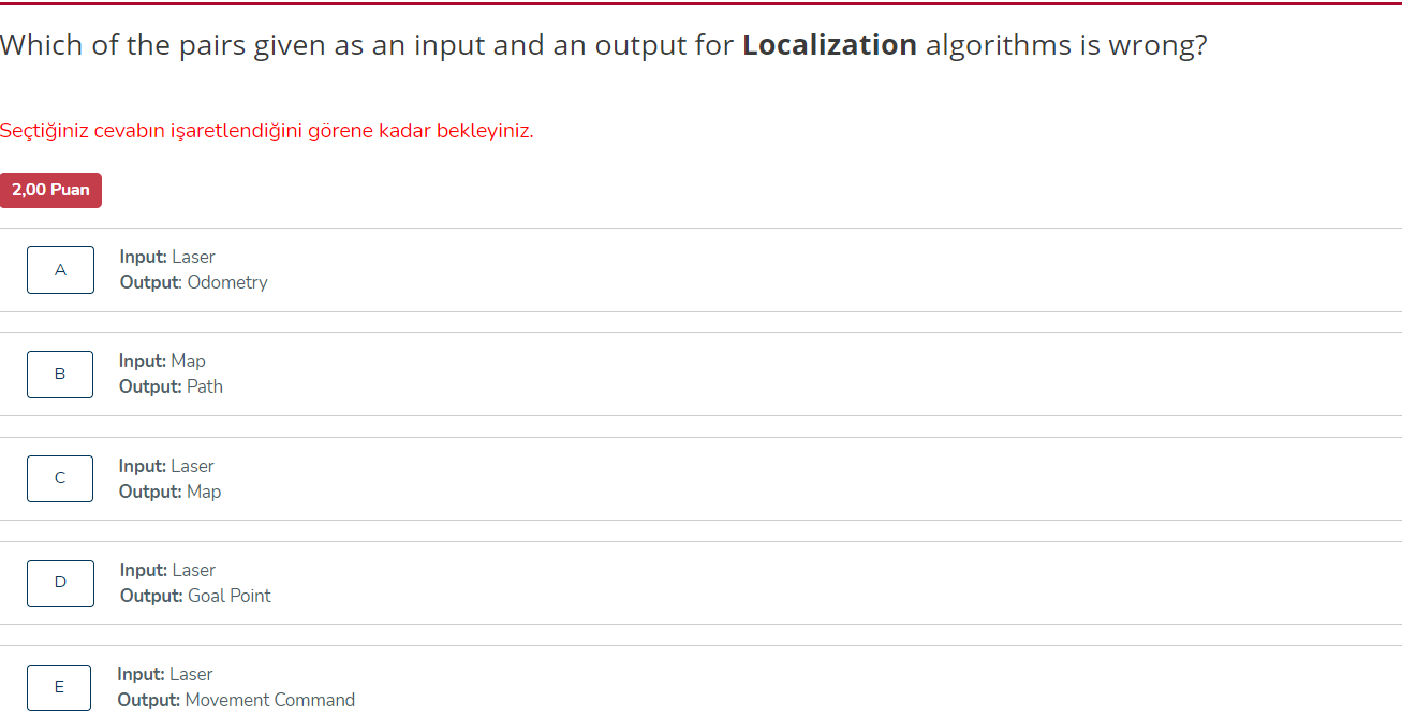
What is “Point Cloud”??



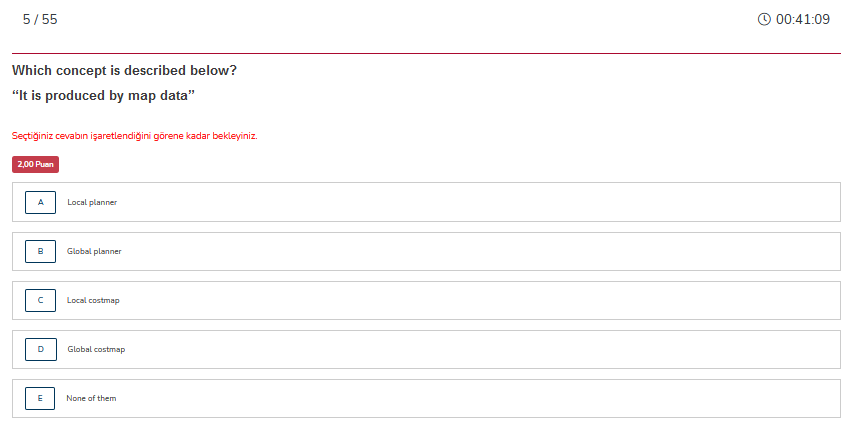
What is the difference between pose and odometry?



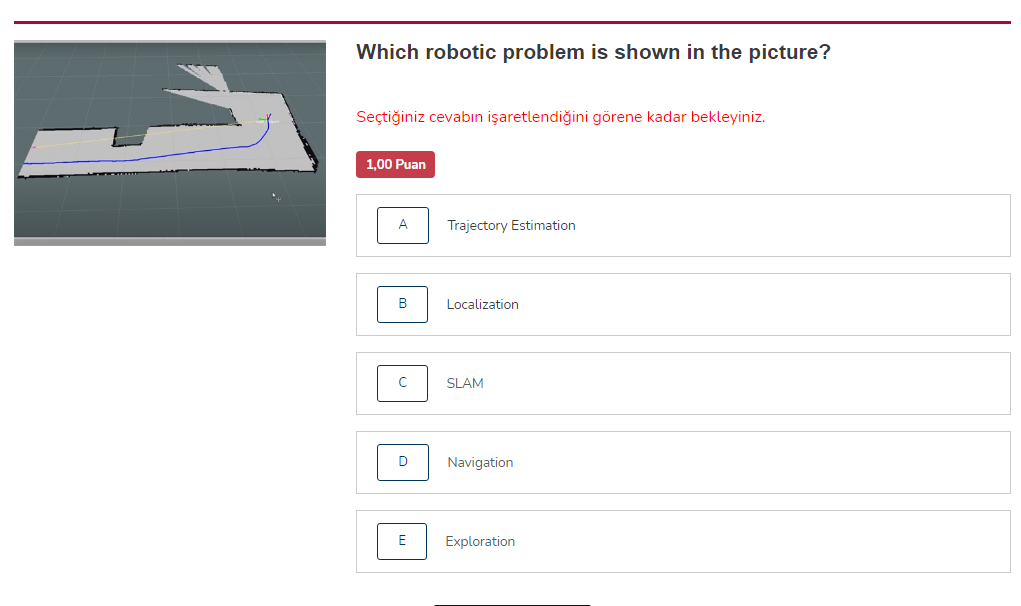
Which of the pairs given as an input and an output for Localization algorithms is wrong?



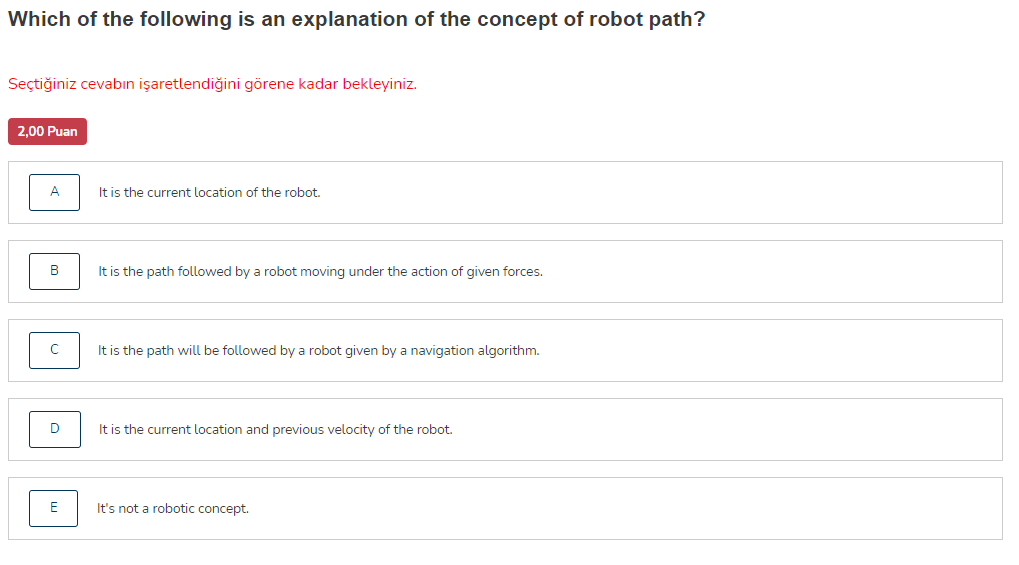
Which concept is described below? “It is produced by map data”??

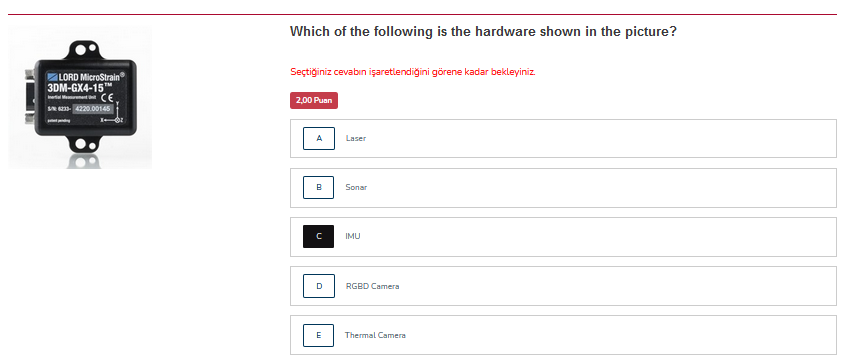


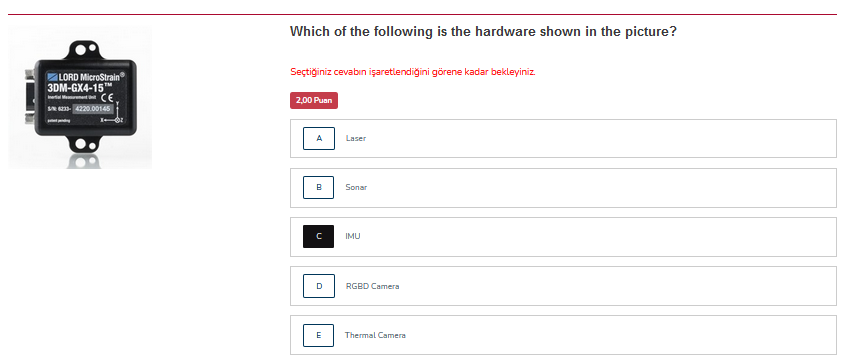
Which robotic problem is shown in the picture??

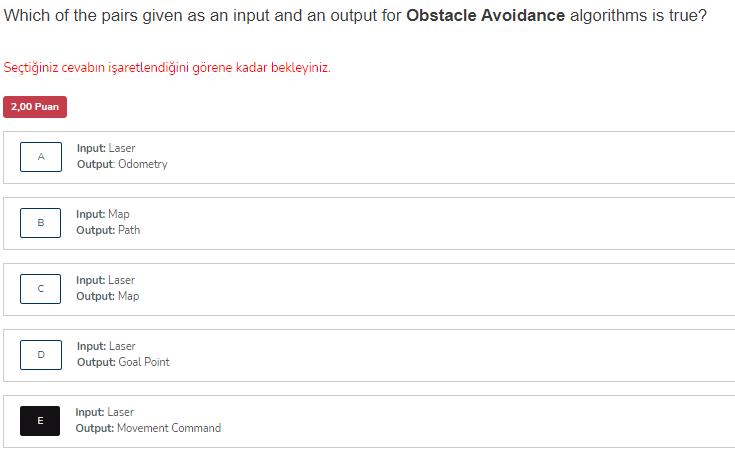


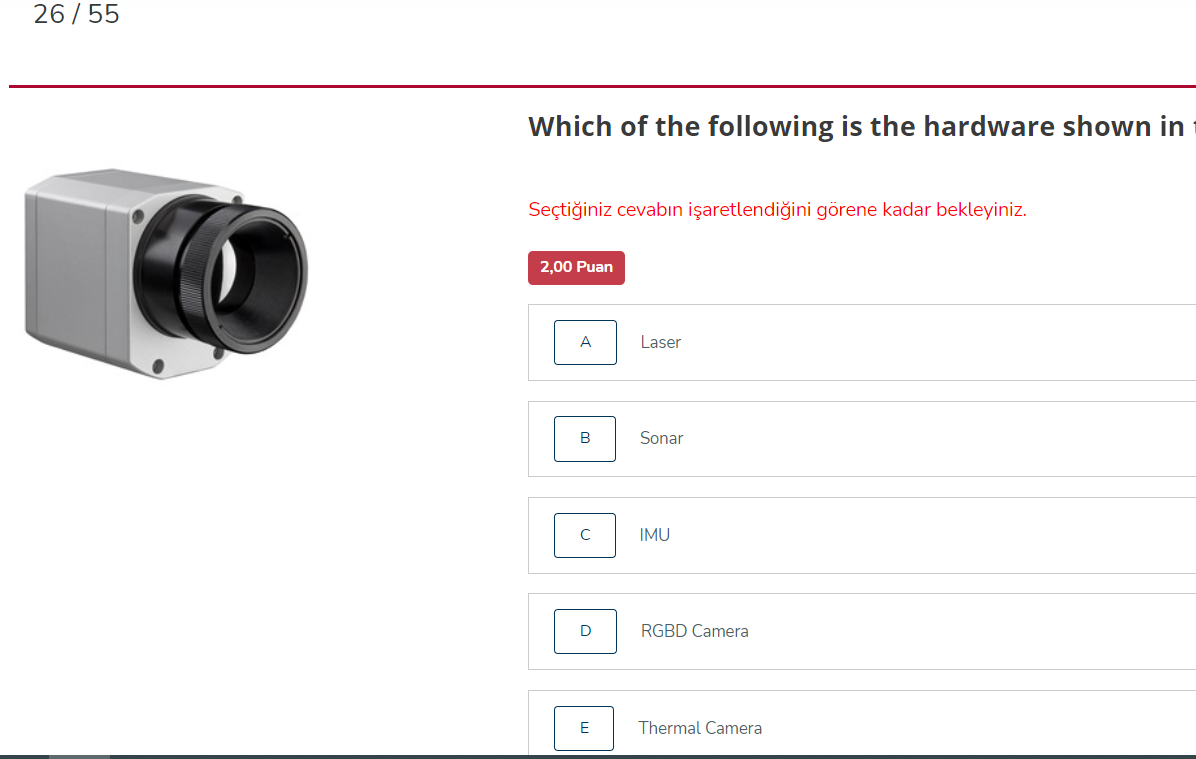
Which of the following is an explanation of the concept of robot path??











Which is a correct expression for fixed wheels??

